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 State Estimation and Coordinated Control for Distributed Electric Vehicles
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 The Dynamics of Vehicles on Roads and on Tracks Supplement to Vehicle System Dynamics
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 Dynamics of Vehicles on Roads and Tracks
 Proceedings of the AHFE 2016 International Conference on Human Factors in Transportation, July 27-31, 2016, Walt Disney World®, Florida, USA
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 DSP, human-to-vehicle interfaces, driver behavior, and safety
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New Trends on System Science and Engineering John Wiley & Sons

Despite a growing body of research and targeted remediation, teenage and novice drivers continue to be six to nine times more likely to die in a crash than they are when they are just a few years older. The World Health Organization reports that road traffic injuries are the leading cause of death globally among 15 to 19 year olds. In light of these crash statistics, understanding the teen driver problem remains of paramount public health importance around the world. The Handbook of Teen and Novice Drivers: Research, Practice, Policy, and Directions provides critical knowledge for a broad range of potential readers, including students, teachers, researchers in academics, industry and the federal government, public policy makers at all levels, insurance companies and automobile manufacturers, driving instructors, and parents and their teens.

Encyclopedia of Automotive Engineering Springer Nature
 This book tackles some of the most challenging problems in state estimation and traction coordinated control systems to improve the dynamic control performance of Distributed Electric Vehicles. The developed methods make it possible to gain more accurate information regarding the vehicle states, ensure more desirable vehicle motions and better robustness in unforeseeable driving environments. Given the impressive features of Distributed Electric Vehicles, including their simple and compact structure, short transmission chains, fast and accurate control response, modular drivetrain design etc., it is widely recognized that they represent an important future development direction and attract many of the brightest engineers and scientists. This book makes a significant contribution to the design of safer and more efficient vehicles.

Proceedings of the 2nd VAE2018, Miskolc, Hungary IOS Press
 The International Symposium on Dynamics of Vehicles on Roads and Tracks is the leading international gathering of scientists and engineers from academia and industry in the field of ground vehicle dynamics to present and exchange their latest innovations and breakthroughs. Established in Vienna in 1977, the International Association of Vehicle System Dynamics (IAVSD) has since held its biennial symposia throughout Europe and in the USA, Canada, Japan, South Africa and China. The main objectives of IAVSD are to promote the development of the science of vehicle dynamics and to encourage engineering applications of this field of science, to inform scientists and engineers on the current state-of-the-art in the field of vehicle dynamics and to broaden contacts among persons and organisations of the various countries engaged in scientific research and development in the field of vehicle dynamics and related areas. IAVSD 2017, the 25th

Symposium of the International Association of Vehicle System Dynamics was hosted by the Centre for Railway Engineering at Central Queensland University, Rockhampton, Australia in August 2017. The symposium focused on the following topics related to road and rail vehicles and trains: dynamics and stability; vibration and comfort; suspension; steering; traction and braking; active safety systems; advanced driver assistance systems; autonomous road and rail vehicles; adhesion and friction; wheel-rail contact; tyre-road interaction; aerodynamics and crosswind; pantograph-catenary dynamics; modelling and simulation; driver-vehicle interaction; field and laboratory testing; vehicle control and mechatronics; performance and optimization; instrumentation and condition monitoring; and environmental considerations. Providing a comprehensive review of the latest innovative developments and practical applications in road and rail vehicle dynamics, the 213 papers now published in these proceedings will contribute greatly to a better understanding of related problems and will serve as a reference for researchers and engineers active in this specialised field.

Computer Vision and Imaging in Intelligent Transportation Systems Springer

Proceedings of Innovative Research and Industrial Dialogue 2016 Centre for Advanced Research on Energy

Proceedings of the 25th International Symposium on Dynamics of Vehicles on Roads and Tracks (IAVSD 2017), 14-18 August 2017, Rockhampton, Queensland, Australia
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The ICMEA2014 will provide an excellent international academic forum for sharing knowledge and results in theory, methodology and applications of Mechanical Engineering and Automation. The ICMEA2014 is organized by Advanced Information Science Research Center (AISRC) and is co-sponsored by Chongqing University, Changsha University of Science & Technology, Huazong University of Science and Technology and China Three Gorges University. This ICMEA2014 proceedings tends to collect the up-to-date, comprehensive and worldwide state-of-art knowledge on mechanical engineering and automation, including control theory and application, mechanic manufacturing system and automation, and Computer Science and applications. All of accepted papers were subjected to strict peer-reviewing by 2-4 expert referees. The papers have been selected for this volume because of quality and the relevance to the conference. We hope this book will not only provide the readers a broad overview of the latest research results, but also provide the readers a valuable summary and reference in these fields. ICMEA2014 organizing committee would like to express our sincere appreciations to all authors for their contributions to this book. We would like to extend our thanks to all the referees for their constructive comments on all papers; especially, we would like to thank to organizing committee for their hard working.

State Estimation and Coordinated Control for Distributed

Electric Vehicles CRC Press

Due to the improvements on electric motors and motor control technology, alternative vehicle power system layouts have been considered. One of the latest is known as distributed drive electric vehicles (DDEVs), which consist of four motors that are integrated into each drive and can be independently controllable. Such an innovative design provides packaging advantages, including short transmission chain, fast and accurate torque response, and so on. Based on these advantages and features, this book takes stability and energy-saving as cut-in points, and conducts investigations from the aspects of Vehicle State Estimation, Direct Yaw Moment Control (DYC), Control Allocation (CA). Moreover, lots of advanced algorithms, such as general regression neural network, adaptive sliding mode control-based optimization, as well as genetic algorithms, are applied for a better control performance.

Springer
 Learn how ART and ADT can reduce cost, time, product recalls, and customer complaints This book provides engineers with the techniques and tools they need to use accelerated reliability testing (ART) and accelerated durability testing (ADT) as key factors to accurately predict a product's quality, reliability, durability, and maintainability during a given time, such as service life or warranty period. It covers new ideas and offers a unique approach to accurate simulation and integration of field inputs, safety, and human factors, as well as accelerated product development, as components of interdisciplinary systems engineering. Beginning with a comprehensive introduction to the subject of ART and ADT, the book covers: ART and ADT as components of an interdisciplinary systems of systems approach Methodology of ART and ADT performance Equipment for ART and ADT technology ART and ADT as sources of initial information for accurate quality, reliability, maintainability, and durability prediction and product accelerated development The economical results of the usage of ART and ADT ART and ADT standardization The book covers the newest techniques in the field and provides many case studies that illuminate how the implementation of ART and ADT can solve previously inaccessible problems in the field of engineering, such as reducing product recalls, cost, and time during design, manufacture, and usage. Professionals will find the answers to how one can carry out ART and ADT technology in a practical manner. Accelerated Reliability and Durability Testing Technology is indispensable reading for engineers, researchers in industry, usage, and academia who are involved in the design of experiments, field simulations, maintenance, reliability, durability, accurate prediction, and product development, and graduate students in related courses.

Proceedings of the 25th International Symposium on Dynamics of Vehicles on Roads and Tracks (IAVSD 2017), 14-18 August 2017, Rockhampton, Queensland, Australia
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The International Symposium on Dynamics of Vehicles on Roads

and Tracks is the leading international gathering of scientists and engineers from academia and industry in the field of ground vehicle dynamics to present and exchange their latest ideas and breakthroughs. The International Association of Vehicle System Dynamics (IAVSD) was established in Vienna in 1977 and has since held its biennial symposia throughout Europe and in the USA, Canada, Japan, South Africa and China. The IAVSD, while celebrating its first 40 years, held the 25th Symposium at Rockhampton, Queensland, Australia in August 2017. The symposium was hosted by the Centre for Railway Engineering at Central Queensland University. The papers presented at the symposium are now published in these Proceedings to provide a comprehensive review of the latest innovative developments and practical applications in road and rail vehicle dynamics. The papers will contribute greatly to a better understanding of related problems and serve as a reference for researchers and engineers active in this specialised field. IAVSD2017 focused on the following topics related to road and rail vehicles and trains: dynamics and stability vibration and comfort suspension steering traction and braking active safety systems advanced driver assistance systems autonomous road and rail vehicles adhesion and friction wheel-rail contact tyre-road interaction aerodynamics and crosswind pantograph-catenary dynamics modelling and simulation driver-vehicle interaction field and laboratory testing vehicle control and mechatronics performance and optimisation instrumentation and condition monitoring environmental considerations

Springer Nature

The three volume set LNAI 7506, LNAI 7507 and LNAI 7508 constitutes the refereed proceedings of the 5th International Conference on Intelligent Robotics and Applications, ICIRA 2012, held in Montreal, Canada, in October 2012. The 197 revised full papers presented were thoroughly reviewed and selected from 271 submissions. They present the state-of-the-art developments in robotics, automation and mechatronics. This volume covers the topics of robot actuators and sensors; robot design, development and control; robot intelligence, learning and linguistics; robot mechanism and design; robot motion analysis and planning; robotic vision, recognition and reconstruction; and planning and navigation.

Smart Cities, Green Technologies and Intelligent Transport Systems Springer

A real-time system is a complex system which is an integral part of an industrial or experimental system, a vehicle or a construction machine. The peculiarity of these systems is that they are driven by real-time targets in distributed environments. Command-control for Real-time Systems presents the calculation of correction for industrial systems of different physical natures, their implementation on real-time target industrial systems (PLC-SCADA, embedded systems with distributed networks, Networked Control Systems) and their validation by simulation. It optimizes industrial processes by the use of automatic tools, industrial computing and communications networks and aims to successively integrate new control laws (linear, nonlinear and fuzzy controllers) so that users can leverage the power of engineering science as an automatic service process optimization while maintaining their high maintainability facilities. Contents 1. Introduction. 2. Modeling Tools, Sébastien Cabaret and Mohammed Chadli. 3. Control Tools, Mohammed Chadli and Hervé Coppier. 4. Application to Cryogenic Systems, Marco Pezzetti, Hervé Coppier and Mohammed Chadli. 5. Applications to a Thermal System and to Gas Systems, Sébastien Cabaret and Hervé Coppier. 6. Application to Vehicles, Elie Kafrouni and Mohammed Chadli. 7. Real-time Implementation, Marco Pezzetti and Hervé Coppier. About the Authors Mohamed Chadli is a senior lecturer and research supervisor at the University of Picardie Jules Verne (UPJV) in France. His main research interests lie in robust control, the diagnosis and fault tolerant control of polytopic systems and applications for automobiles. He is a senior member of the IEEE, and Vice President of the AAI Club as part of SEE-France. He is the author/co-author of 3 books, book chapters and more than 100 articles published in international journals and conferences. Hervé Coppier is a lecturing researcher at ESIEE-Amiens in France. He has collaborated with industrialists in the field of automation and industrial computing, particularly with CERN, and has spearheaded various international European projects.

Product Performance Evaluation using CAD/CAE Academic Press Current events help to emphasise the importance of the analysis and management of risk to planners and researchers around the world. Natural hazards such as floods, earthquakes, landslides, fires and others have always affected human societies. The more recent emergence of the importance of man-made hazards is a consequence of the rapid technological advances made in the last few centuries. The interaction of natural and anthropogenic risks adds to the complexity of the problems. Presented at the 12th International Conference on Risk Analysis and Hazard Mitigation,

the included research works cover a variety of topics related to risk analysis and hazard mitigation, associated with both natural and anthropogenic hazards.

Advances in Human Aspects of Transportation: Part II Elsevier Human Factors and Ergonomics have made a considerable contribution to the research, design, development, operation and analysis of transportation systems which includes road and rail vehicles and their complementary infrastructure, aviation and maritime transportation. This book presents recent advances in the Human Factors aspects of Transportation. These advances include accident analysis, automation of vehicles, comfort, distraction of drivers (understanding of distraction and how to avoid it), environmental concerns, in-vehicle systems design, intelligent transport systems, methodological developments, new systems and technology, observational and case studies, safety, situation awareness, skill development and training, warnings and workload. This book brings together the most recent human factors work in the transportation domain, including empirical research, human performance and other types of modeling, analysis, and development. The issues facing engineers, scientists, and other practitioners of human factors in transportation research are becoming more challenging and more critical. The common theme across these sections is that they deal with the intersection of the human and the system. Moreover, many of the chapter topics cross section boundaries, for instance by focusing on function allocation in NextGen or on the safety benefits of a tower controller tool. This is in keeping with the systemic nature of the problems facing human factors experts in rail and road, aviation and maritime research- it is becoming increasingly important to view problems not as isolated issues that can be extracted from the system environment, but as embedded issues that can only be understood as a part of an overall system.

The Dynamics of Vehicles on Roads and on Tracks Supplement to Vehicle System Dynamics Springer Science & Business Media Discover the latest research in path planning and robust path tracking control In Autonomous Road Vehicle Path Planning and Tracking Control, a team of distinguished researchers delivers a practical and insightful exploration of how to design robust path tracking control. The authors include easy to understand concepts that are immediately applicable to the work of practicing control engineers and graduate students working in autonomous driving applications. Controller parameters are presented graphically, and regions of guaranteed performance are simple to visualize and understand. The book discusses the limits of performance, as well as hardware-in-the-loop simulation and experimental results that are implementable in real-time. Concepts of collision and avoidance are explained within the same framework and a strong focus on the robustness of the introduced tracking controllers is maintained throughout. In addition to a continuous treatment of complex planning and control in one relevant application, the Autonomous Road Vehicle Path Planning and Tracking Control includes: A thorough introduction to path planning and robust path tracking control for autonomous road vehicles, as well as a literature review with key papers and recent developments in the area Comprehensive explorations of vehicle, path, and path tracking models, model-in-the-loop simulation models, and hardware-in-the-loop models Practical discussions of path generation and path modeling available in current literature In-depth examinations of collision free path planning and collision avoidance Perfect for advanced undergraduate and graduate students with an interest in autonomous vehicles, Autonomous Road Vehicle Path Planning and Tracking Control is also an indispensable reference for practicing engineers working in autonomous driving technologies and the mobility groups and sections of automotive OEMs.

Mechanical and Electronics Engineering III John Wiley & Sons Volume is indexed by Thomson Reuters CPCI-S (WoS). These peer-reviewed proceedings comprise the papers presented at a conference whose main theme was Mechanical and Electronics Engineering. The main goal of the event was to provide an international scientific forum for the exchange of new ideas in a number of fields and for in-depth interaction via discussions with peers from around the world. Core areas of Information and Network Technology, plus multidisciplinary, interdisciplinary and applied aspects were covered.

Dynamics of Vehicles on Roads and Tracks Springer World-class experts from academia and industry assembled at the sixth Biennial Workshop on Digital Signal Processing (DSP) for In-Vehicle Systems at Korea University, Seoul, Korea in 2013. The Workshop covered a wide spectrum of automotive fields, including in-vehicle signal processing and cutting-edge studies on safety, driver behavior, infrastructure, in-vehicle technologies. Contributors to this volume have expanded their contributions to the Workshop into full chapters with related works, methodology, experiments, and the analysis of the findings. Topics in this volume include: DSP technologies for in-vehicle systems Driver status and behavior monitoring In-Vehicle dialogue systems and

human machine interfaces In-vehicle video and applications for safety Passive and active driver assistance technologies Ideas and systems for autonomous driving Transportation infrastructure Proceedings of the AHFE 2016 International Conference on Human Factors in Transportation, July 27-31, 2016, Walt Disney World®, Florida, USA CRC Press

Acts as single source reference providing readers with an overview of how computer vision can contribute to the different applications in the field of road transportation This book presents a survey of computer vision techniques related to three key broad problems in the roadway transportation domain: safety, efficiency, and law enforcement. The individual chapters present significant applications within those problem domains, each presented in a tutorial manner, describing the motivation for and benefits of the application, and a description of the state of the art. Key features: Surveys the applications of computer vision techniques to road transportation system for the purposes of improving safety and efficiency and to assist law enforcement. Offers a timely discussion as computer vision is reaching a point of being useful in the field of transportation systems. Available as an enhanced eBook with video demonstrations to further explain the concepts discussed in the book, as well as links to publically available software and data sets for testing and algorithm development. The book will benefit the many researchers, engineers and practitioners of computer vision, digital imaging, automotive and civil engineering working in intelligent transportation systems. Given the breadth of topics covered, the text will present the reader with new and yet unconceived possibilities for application within their communities.

Accelerated Reliability and Durability Testing Technology Springer

This book contains a selection of articles from The 2016 World Conference on Information Systems and Technologies (WorldCIST'16), held between the 22nd and 24th of March at Recife, Pernambuco, Brazil. WorldCIST is a global forum for researchers and practitioners to present and discuss recent results and innovations, current trends, professional experiences and challenges of modern Information Systems and Technologies research, together with their technological development and applications. The main topics covered are: Information and Knowledge Management; Organizational Models and Information Systems; Software and Systems Modeling; Software Systems, Architectures, Applications and Tools; Multimedia Systems and Applications; Computer Networks, Mobility and Pervasive Systems; Intelligent and Decision Support Systems; Big Data Analytics and Applications; Human-Computer Interaction; Health Informatics; Information Technologies in Education; Information Technologies in Radiocommunications.

Automotive Engineering International Centre for Advanced Research on Energy

This book covers the start-of-the-art research and development for the emerging area of autonomous and intelligent systems. In particular, the authors emphasize design and validation methodologies to address the grand challenges related to safety. This book offers a holistic view of a broad range of technical aspects (including perception, localization and navigation, motion control, etc.) and application domains (including automobile, aerospace, etc.), presents major challenges and discusses possible solutions.

Safe, Autonomous and Intelligent Vehicles Springer Nature

This book presents the proceedings of the second Vehicle Engineering and Vehicle Industry conference, reflecting the outcomes of theoretical and practical studies and outlining future development trends in a broad field of automotive research. The conference's main themes included design, manufacturing, economic and educational topics.

Proceedings of the 26th Symposium of the International Association of Vehicle System Dynamics, IAVSD 2019, August 12-16, 2019, Gothenburg, Sweden Proceedings of Innovative Research and Industrial Dialogue 2016

This book presents a selection of papers from the 2017 World Conference on Information Systems and Technologies (WorldCIST'17), held between the 11st and 13th of April 2017 at Porto Santo Island, Madeira, Portugal. WorldCIST is a global forum for researchers and practitioners to present and discuss recent results and innovations, current trends, professional experiences and challenges involved in modern Information Systems and Technologies research, together with technological developments and applications. The main topics covered are: Information and Knowledge Management; Organizational Models and Information Systems; Software and Systems Modeling; Software Systems, Architectures, Applications and Tools; Multimedia Systems and Applications; Computer Networks, Mobility and Pervasive Systems; Intelligent and Decision Support Systems; Big Data Analytics and Applications; Human-Computer Interaction; Ethics, Computers & Security; Health Informatics; Information Technologies in Education; and Information Technologies in Radiocommunications.

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