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Pi Localization and autonomous path planning

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<u>for Robot</u>	<i>navigation</i>	<u>results</u>
<u>Navigation</u>	<i>robot with</i>	<u>Outdoor</u>
<u>using</u>	ROS	<u>stereo SLAM</u>
<u>Cartographer</u>	<i>(Raspberry pi</i>	<u>with RTAB-</u>
<u>Localization</u>	<i>+ YDLIDAR)</i>	<u>Map ROS2</u>
<u>and Mapping</u>	ROS	<i>Essentials:</i>
<u>(SLAM) on</u>	<i>Autonomous</i>	<i>Robot</i>
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<u>on Raspberry</u>	<i>Topics</i>	<i>\u0026</i>
<u>Pi 4 ~</u>	<i>Packages</i>	Localization
<u>RPILIDAR,</u>	<i>RosMaster</i>	and Visual
<u>Xbox 360</u>	_____	Servoing, Full
<u>Kinect Demos</u>	DIY Lidar	Path,
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