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this is probably the greatest thing of the robotic arm it has a distance sensor, and it can react to that i will show you how you are able to program that by you own. it is written in c++ the first thing you see is this `#define trigPin 7 //toevoegen aan code #define echoPin 6 #define led 13 #include <Servo.h> now we are including the servo's, led, and the distance sensor to the code. you don't ...`

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