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problem, Kawasaki Robot has a unique off-line teaching system called KCONG (Kawasaki Common Offline NC data Generator) that makes it possible to teach complicated motions in a highly precise manner. For example, in the case where works are machined by cutting tools mounted on robots, KCONG captures 3D models of applicable works first.

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The KCONG (Kawasaki Common Offline NC data Generator) offline programming software is used to automatically generate a robot's welding path based off of workpiece geometry. 3D CAD part and tooling data is imported into KCONG along with a library of supplied Kawasaki robot models. The user then inputs application parameters and selects workpiece geometry to automatically generate the robot welding path.

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