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the SD card that you can. Installing OpenCV 3.2 Computer Vision - Second Robotics OpenCV (Open Source Computer Vision Library) is an open-source computer vision library with bindings for C++, Python, and Java and supports all major operating systems. It can take advantage of multi-core processing and features GPU acceleration for real-time operation.

Start cmake-gui. Select the opencv source code folder and the folder where binaries will be built (the 2 upper forms of the interface). Press the configure button. You will see all the opencv build parameters in the central interface.

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716 Pull Requests have been merged and 588 Issues in our bug tracker have been closed since OpenCV 3.2. Additionally, we've run OpenCV through some strict static analyser tools and fixed the detected problems. So, OpenCV 3.3 should hopefully be very stable and dependable release.

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run pip install opencv-python-headless if you need only main modules; run pip install opencv-contrib-python-headless if you need both main and contrib modules (check extra modules listing from OpenCV documentation) Import the package: import cv2. All packages contain haarcascade files. cv2.data.haarcascades can be used as a shortcut to the data folder. For example:

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